Multiphysics Modeling for Equipment Performance Analysis and Control Design

Jon Ebert SC Solutions, Inc. jle@scsolutions.com

May, 2018 Copyright © 2018, SC Solutions, Inc. All Rights Reserved

Overview

□ History of Modeling at SC (and before)

• Background 1980 - 2018

Purpose of Modeling

- Equipment Design
- o Real-time Feedback Control

Examples

- Semiconductor Equipment
- Advanced Materials
- o Miscellaneous

Summary

History

1980's

- In early 80's, modeling was mostly FORTRAN codes
 - To be a "modeler", you also needed to be a programmer (of sorts)
 - Model development took months or years.

• Convective heat transfer

- Natural convection (an 80x80 grid was big).
- Boundary layer theory (Stan5).
- By late 80's increase computer power leads to big advances.

o Radiation heat transfer

- Tables of view factor formula
- Ray Tracing (slow, but capable of complex geometry).
- Direct Simulation Monte Carlo (DSMC) solves PVD problems.

• Radiative properties

- Improving methods of measurement (FTIR, spectrometers, ...)
- Mie Scattering by small particles used better measurements and better codes









History

1990's (SC's Control Division – 1996)

• Significant increases in computing power



- Development of SC's ray trace and modeling capabilities
 - Driven by Consulting in Semiconductor industry.
 - New ray trace codes allowed very fast models of conduction/radiation dominated problems.
 - Models are now C-code, which makes them platform agnostic.
 - Resulting models run faster than real-time
- Transition to matrix-friendly tools (Matlab, Matrix_x), the problem got much more user friendly.
 - Resulting models were further improved to make them even faster.
- With models faster than real-time, the feedback control problem is changed Model-based Control design.
 - Model-based control enables more complicated control strategies.
 - Use models to do virtual sensing, model-based estimators, etc.









History

2000's +

- The models we build are good for high temperature conduction/radiation dominated problems.
 - Convection handled as a boundary condition. Accurate directional radiative properties and semitransparent media.
- Chemical Vapor Deposition, Thermal Stress, Convection, ... our approach had serious limits. FEM is required.

• 2006 – SC found COMSOL!

- Equation-based approach appealing.
- My first model: natural convection : 1983 1 year, 2006 1hr.
- More complex "modeling for design" is major advantage.
- The recent addition of surface-to-surface radiation very good (accurate).
- COMSOL is a powerful tool for equipment design and evaluation.
- For fast models (100+ times faster than real-time), we use COMSOL to develop *old-fashioned* correlations.







Overview

□ History of Modeling at SC (and before)

Background 1980 - 2018

Purpose of Modeling

- Equipment Design
- o Real-time Feedback Control

Examples

- Semiconductor Equipment
- Advanced Materials
- o Miscellaneous

G Summary

Purpose of Modeling

Using COMSOL for "Fast Model" inputs



Overview

□ History of Modeling at SC (and before)

Background 1980 - 2018

D Purpose of Modeling

- Equipment Design
- o Real-time Feedback Control

Examples

- Semiconductor Equipment
- Advanced Materials
- o Miscellaneous

G Summary

Semiconductor Processing:

Rapid Thermal Processing

Generic RTP System



Tungsten Halogen Lamps

 $D \sim 2-3 \text{ mm}$

The lamp filaments are usually coils (helix). Sometimes they are coils of coils, that is, a long coil of wire is coiled again with a larger radius.



Geometric effects can cause the "effective" emissivity to be larger than the emissivity of the metal surface itself.

May, 2018 Copyright © 2018, SC Solutions, Inc. All Rights Reserved

Closed-loop Soak

Closed-loop control within COMSOL

Closed-loop T vs time (soak)



May, 2018 Copyright © 2018, SC Solutions, Inc. All Rights Reserved

Overview

□ History of Modeling at SC (and before)

Background 1980 - 2018

D Purpose of Modeling

- Equipment Design
- o Real-time Feedback Control

Examples

- Semiconductor Equipment
- Advanced Materials
- o Miscellaneous

Summary

Advanced Materials:

Metal Organic Chemical Vapor Deposition (MOCVD) for production of LED's



Model of Valence Equipment's MOCVD Chamber

- □ Chamber geometry details obtained from U.S. Patent 8778079.
- □ Materials, if specified in patent, are indicated in figure.



15

Temperature Distributions

Wafer carrier heated by tungsten filaments primarily by radiative heat transfer.



Heat Transfer Coefficient Correlation Derived from Simulations



17

Advanced Materials:

Another MOCVD System (one we can show data)



Commercial MOCVD 3 x 2" Reactor (three wafers of 2" diameter)



Wafer Temperature



May, 2018 Copyright © 2018, SC Solutions, Inc. All Rights Reserved

Model Validation with Photoluminescence (PL) Data

Temperature distribution on wafer obtained from PL-temperature correlation in the literature. COMSOL model simulated with actual heater inputs for the processed wafer with PL data.





Miscellaneous:

Modeling of Electro-Chemical-Mechanical Polishing (ECMP) Process



ECMP Modeling (Electrochemistry)



- **L** Electro-Chemical Mechanical Planarization (ECMP) can be used in IC fabs for polishing semiconductor wafers.
- **ECMP** uses a combination of mechanical pressure, chemical reaction, and electrochemistry to remove the metallic (copper) layers between steps such as thin film deposition and etch.
- The copper layer acts as anode and the conductive layer on polishing pad acts as cathode with the thin layer of electrolyte flowing between the rotating pad and wafer.

ECMP Equations



V.

27.0 mm

A simple 2D geometry for ECMP allowed focus on electrochemistry.

- Electrolyte enters from the left with linear velocity profile (U).
- Polishing occurs at the copper anode (top "wall") which is moving at velocity U₀ with respect to the cathode on the pad (bottom "wall").

Insulation

27.0 mm

 V_2 (ground)

27.0 mm

1 mm

H 14

COMSOL Model Results (including Experimental Validation)



- Copper polish rates in Å/minute computed from the gradient of the copper complex flux at anode.
- Rate decreases in flow direction as water available for the reaction decreases.
- Very good agreement with our experimental results.

25

Overview

□ History of Modeling at SC (and before)

Background 1980 - 2018

Purpose of Modeling

- Equipment Design
- o Real-time Feedback Control

Examples

- Semiconductor Equipment
- Advanced Materials
- o Miscellaneous

G Summary

Summary

SC has used COMSOL for two main purposes

- Design and analysis of equipment performance.
- Augment SC's fast models for model-based control design.
- Our main areas include thermophysics and we've worked on many projects over the years.
 - Equipment: RTP, CMP, Etch, CVD, MOCVD, Epi, MBE, Sputtering, PVD, ...
 - Physics: Heat transfer, Fluid flow, Species transport, Electrochemistry, Thermal stress,...

Our business consists of two parts:

- Real-time Model-based Control
- Engineering Consulting



SC SOLUTIONS

Thank You